

# Nonparametric estimation under shape constraints, part 2

Piet Groeneboom, Delft University

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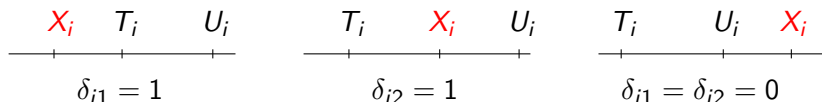
## What to expect?

- Theory and open problems for interval censoring, case 2.
- Same for the bivariate current status model.
- Convex regression.
- The convex envelope of one-sided Brownian motion without drift.
- Does bootstrapping from the Grenander estimate work for global statistics?

## Interval censoring, case 2

$X_1, X_2, \dots, X_n \sim F_0$ .

Instead of observing the  $X_i$ 's, one only observes  $X_i \leq T_i$  or  $X_i \in (T_i, U_i]$  or  $X_i > U_i$ , for some random pair  $(T_i, U_i)$ , where  $T_i < U_i$ ,  $(T_i, U_i)$  independent of  $X_i$ .



So, instead of observing  $X_i$ 's, one observes

$$(T_i, U_i, \delta_{i1}, \delta_{i2}) = (T_i, U_i, \mathbf{1}_{\{X_i \leq T_i\}}, \mathbf{1}_{\{X_i \in (T_i, U_i]\}}).$$

where  $(T_i, U_i)$  is independent of  $X_i$ .

## Interval censoring model

We want to estimate the unknown distribution function  $F_0$  of  $X_i$ , based on the data  $(T_i, U_i, \delta_{i1}, \delta_{i2})$ .

The log likelihood function in  $F$  (conditional on the  $(T_i, U_i)$ 's) is, taking  $\delta_{i3} = 1 - \delta_{i1} - \delta_{i2}$ :

$$\sum_{i=1}^n \{ \delta_{i1} \log F(T_i) + \delta_{i2} \log(F(U_i) - F(T_i)) + \delta_{i3} \log(1 - F(U_i)) \}.$$

The (nonparametric) maximum likelihood estimator (MLE)  $\hat{F}_n$  maximizes the log likelihood over the class of *all* distribution functions  $F$ .

## Interval censoring, case 2, algorithms

Algorithms for computing the MLE:

① **EM algorithm**

Start for example with the discrete uniform distribution on a subset of the observation points and iterate:

$$F^{(m+1)}(t) = n^{-1} \sum_{i=1}^n P^{(m)} \{X \leq t | T_j, U_j, \delta_{j1}, \delta_{j2}, j = 1, \dots, n\}$$

Very slow!

- ② **Iterative convex minorant algorithm** (Groeneboom (1991), using the modification in Jongbloed (1998)).
- ③ **Support reduction algorithm** (Groeneboom, Jongbloed, and Wellner (2008)).  
Iterative cone projection, starting with a minimal “feasible” (finite likelihood) solution. Available in R (MLEcens).

## Interval censoring, case 2, non-separated case

Asymptotic local distribution?

Conjecture (Groeneboom (1991))

Let  $G$  be the distribution function of  $(T_i, U_i)$  and let  $F_0$  and  $G$  be continuously differentiable at  $t_0$  and  $(t_0, t_0)$ , respectively, with *strictly positive* derivatives  $f_0(t_0)$  and  $g(t_0, t_0)$ . Let  $\hat{F}_n$  be the MLE of  $F_0$ . Then

$$(n \log n)^{1/3} \left\{ \hat{F}_n(t_0) - F_0(t_0) \right\} / \left\{ 6f_0(t_0)^2 / g(t_0, t_0) \right\}^{1/3} \xrightarrow{\mathcal{D}} Z,$$

where  $Z = \operatorname{argmax}_t \{W(t) - t^2\}$ .

Still not proved!

## Local rate

- ① Shown in Groeneboom (1991): the conjecture is true for a “toy” estimator, obtained by **doing one step of the iterative convex minorant algorithm**, starting the iterations at the underlying distribution function  $F_0$ .  
Birgé (1999) has constructed a histogram-type estimator, achieving the local rate  $(n \log n)^{1/3}$  in this model. (Minimax rate is faster than the rate in the current status model!)
- ② If the times  $T_i$  and  $U_i$  are **separated**, that is:

$$\mathbb{P}\{U_i - T_i < \epsilon\} = 0,$$

for some  $\epsilon > 0$ , the rate drops to  $n^{1/3}$ .

- ③ The asymptotic distribution of the MLE can in this case be proved to be the same as the distribution of the toy estimator (Groeneboom (1996)). Limit distribution is again  $Z = \operatorname{argmax}\{W(t) - t^2\}$ . Variance: Wellner (1995).

# Lucien Birgé and Jon Wellner





## Smooth functionals for interval censoring

- The nonlinear aspect of the functional is negligible.

$$\sqrt{n} \left\{ K(\hat{F}_n) - K(F_0) \right\} = \sqrt{n} \int \kappa_{F_0} d(\hat{F}_n - F_0) + o_p(1).$$

- Transformation to the observation space measure.

$$\int \kappa_{F_0} d(\hat{F}_n - F_0) = - \int \theta_{\hat{F}_n}(t, \delta) dQ_0(t, \delta),$$

where  $\theta_{F_0}(t, \delta)$  and  $\theta_{\hat{F}_n}(t, \delta)$  are defined via the solutions of integral equations. No explicit solutions for  $\theta_{F_0}(t, \delta)$  and  $\theta_{\hat{F}_n}(t, \delta)$ !

## Smooth functionals for interval censoring

- Use that  $\hat{F}_n$  is the MLE.

Replace  $\theta_{\hat{F}_n}$  by  $\bar{\theta}_{\hat{F}_n}(t, \delta)$ , where  $\bar{\theta}_{\hat{F}_n}(t, \delta)$  satisfies:

$$\int \bar{\theta}_{\hat{F}_n}(t, \delta) dQ_n = 0, \quad (1)$$

and write:

$$\begin{aligned} & \int \kappa_{F_0} d(\hat{F}_n - F_0) \stackrel{\text{step 2}}{=} - \int \theta_{\hat{F}_n} dQ_0 \\ & \stackrel{(1)}{=} \int \bar{\theta}_{\hat{F}_n} d(Q_n - Q_0) - \int \left\{ \theta_{\hat{F}_n} - \bar{\theta}_{\hat{F}_n} \right\} dQ_0. \end{aligned}$$

- Asymptotic variance equals information lower bound.

$$\int \bar{\theta}_{\hat{F}_n} d(Q_n - Q_0) = \int \theta_{F_0} d(Q_n - Q_0) + o_p\left(n^{-1/2}\right),$$

In: Geskus and Groeneboom (1996, 1997 and 1999).

## SMLE and MSLE?

Once the **MLE**  $\hat{F}_n$  is computed, we can easily compute the **SMLE** by

$$\int \mathbb{K}_h(t - x) d\hat{F}_n(x), \quad \mathbb{K}_h(u) = \int_{-\infty}^{u/h} K(x) dx.$$

Theory has to use **local smooth functional theory** again, see Groeneboom and Ketelaars (2011).

Computing the **MSLE** is harder. Local limit for separated case is determined in Groeneboom (2012). Proof is based on the solution of a non-linear integral equation.

## Deconvolution

$$Z_i = X_i + Y_i \sim h_0, \quad h_0(z) = \int g(z - x) dF_0(x), \quad z \geq 0,$$

$g$  is a known decreasing continuous density on  $[0, \infty)$ .

$F_0$  has support, contained in  $[0, \infty)$ .

MLE maximizes over  $F$ :

$$\sum_{i=1}^n \log \int g(Z_i - x) dF(x).$$

### Conjecture (Groeneboom (1991))

*At an interior point  $t$  of the support of  $F_0$ :*

$$n^{1/3} \left( \frac{g(0)^2}{4f_0(t)h_0(t)} \right)^{1/3} \{ \hat{F}_n(t) - F_0(t) \} \rightarrow Z,$$

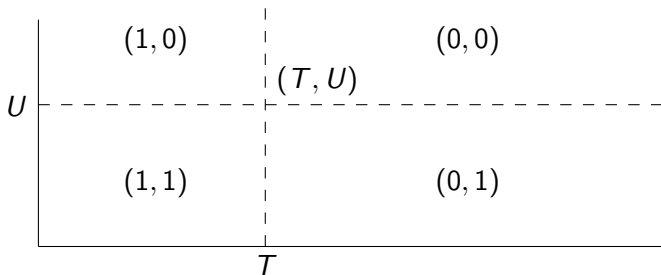
where  $Z = \operatorname{argmax}\{W(t) - t^2\}$ .

## Bivariate current status I

In the bivariate current status model the observations consist of a quadruple  $(T, U, \delta_1, \delta_2)$ , where

$$\delta_1 = 1_{\{X \leq T\}}, \delta_2 = 1_{\{Y \leq U\}}, \quad (2)$$

and  $(X, Y)$  is independent of the observation  $(T, U)$ .



## Bivariate current status II

A maximum likelihood estimator  $\hat{F}_n$  of  $F_0$ , the distribution function of  $(X, Y)$ , maximizes

$$\begin{aligned} & \int \delta_1 \delta_2 \log F(u, v) d\mathbb{P}_n + \int \delta_1 (1 - \delta_2) \log \{F_1(u) - F(u, v)\} d\mathbb{P}_n \\ & + \int (1 - \delta_1) \delta_2 \log \{F_2(v) - F(u, v)\} d\mathbb{P}_n \\ & + \int (1 - \delta_1)(1 - \delta_2) \log \{1 - F_1(u) - F_2(v) + F(u, v)\} d\mathbb{P}_n \end{aligned}$$

over  $F$ , where  $F_1$  and  $F_2$  are the first and second marginal dfs of  $F$ , respectively, and  $\mathbb{P}_n$  is the empirical measure of the observations.

**Difficulty:** we cannot assume that the mass is located in the observation points.

Preliminary reduction algorithm to find the points of possible mass.

## Theorem (Groeneboom (2013))

Consider an interior point  $(t, u)$ , and define the square  $A_n$ , with midpoint  $(t, u)$ , by:

$$A_n = [t - n^{-1/6}, t + n^{-1/6}] \times [u - n^{-1/6}, u + n^{-1/6}].$$

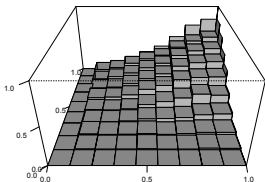
Then, under some regularity conditions, the plug-in estimator

$$\tilde{F}_n(t, u) \stackrel{\text{def}}{=} \frac{\int_{A_n} \delta_1 \delta_2 d\mathbb{P}_n(v, w, \delta_1, \delta_2)}{\int_{A_n} d\mathbb{G}_n(v, w)}, \quad (3)$$

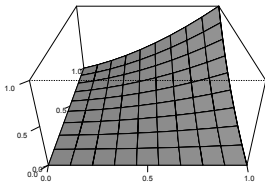
where  $\mathbb{G}_n$  is the empirical distribution function of the observations  $(T_i, U_i)$ , satisfies:

$$n^{1/3} \left\{ \tilde{F}_n(t, u) - F_0(t, u) \right\} \xrightarrow{\mathcal{D}} N(\beta, \sigma^2),$$

where  $N(\beta, \sigma^2)$  is a normal distribution with (specified) parameters  $\beta$  and  $\sigma^2$ .



(a) Plug-in estimate



(b)  $F_0(x, y) = \frac{1}{2}xy(x + y)$

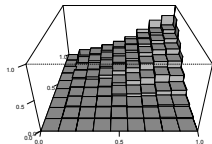
**Figure:** Plug-in estimate for a sample of size  $n = 1000$  from  $F_0(x, y) = \frac{1}{2}xy(x + y)$  on  $[0, 1]^2$ .

The grid has a width of order  $n^{-1/3}$ , but the binwidth of the estimator is of order  $n^{-1/6}$ !

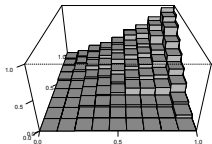
The plug-in estimate is **not** a distribution function (for has -some- negative masses)!



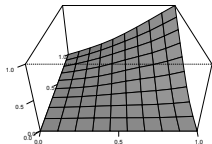
The plug-in estimate is compared with the **MLE** on a grid and smoothed maximum likelihood estimator (**SMLE**) (taking bandwidths  $n^{-1/6}$  in both directions) in a simulation study in Groeneboom (2013).



(a) Plug-in



(b) MLE



(c) SMLE

**Figure:** MLE, SMLE and plug-in estimate for a sample of size  $n = 1000$  from  $F_0(x, y) = \frac{1}{2}xy(x + y)$  on  $[0, 1]^2$ .

The **SMLE** is (modulo boundary correction) defined by

$$\hat{F}_{nh}^{(SML)}(t, u) = \int \mathbb{K}_h(t - v) \mathbb{K}_h(u - w) d\hat{F}_n(v, w),$$

where, for a symmetric kernel  $K$ ,

$$\mathbb{K}_h(x) = \int_{-\infty}^{x/h} K(y) dy,$$

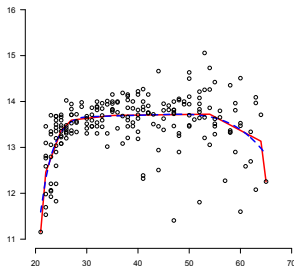
and  $\hat{F}_n$  is the maximum likelihood estimator on a grid.

- 1 SMLE will have rate  $n^{-1/3}$ , if bandwidth  $\asymp n^{-1/6}$ .
- 2 We can probably achieve higher rates for the SMLE, but then we have to use higher order kernels.
- 3 Rate of the MLE is unknown.
- 4 Certain minimax calculations suggest that the rate for the MLE will contain logarithmic factors, causing a rate slower than  $n^{-1/3}$ .

## Convex regression

The relationship between **age** and **log(income)** for Canadian income data can be expected to be **concave**.

We can estimate this relationship only using the concavity restriction.



**Figure:** Concave cubic spline estimate with 5 knots at equal quantile distances (Meyer (2008), blue, dashed) and nonparametric isotonic estimate (red)

- For the usual cubic spline estimation one would have to specify the location of the knots in advance. For example, the estimate in Meyer (2008) uses equal quantile distances.
- The isotonic least squares estimate chooses the locations of the knots automatically. It minimizes the criterion

$$\sum_{i=1}^n \{Y_i - f(t_i)\}^2$$

just under the restriction that  $f$  is convex or concave.

# The nonparametric convex LS estimate

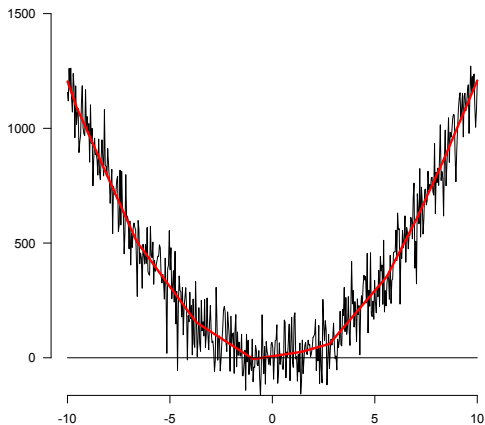


Figure:  $12x^2 + \text{normals}$

## Local limit distribution of the convex regression estimate

$n^{2/5}\{\hat{f}_n(t) - f_0(t)\}$  converges in distribution to the value at zero of the limit, as  $c \rightarrow \infty$ , of the minimizer  $f_c$  of the quadratic form

$$\frac{1}{2} \int_{-c}^c f(x)^2 dx - \int_{-c}^c f(x) d(W(x) + 4x^3), \quad f(\pm c) = 12c^2,$$

where  $W$  is standard two-sided Brownian motion, originating from zero.

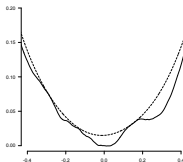


Figure: The functions  $Y$  (solid) and  $H$  (dashed) for standard two-sided Brownian motion on  $[-0.4, 0.4]$ .

The limit is the **second derivative** of the unique **cubic spline**  $H$  lying above and touching  $Y =$  **integrated Brownian motion**  $+t^4$ , **the envelope**: Groeneboom, Jongbloed, and Wellner (2001b)

**Open problem**: are the points of touch isolated?

## The nonparametric convex LS estimate

The nonparametric convex LS estimate will probably be **asymptotically locally minimax** in the same way as the Grenander estimator, but a proof of this fact is still lacking!



Figure: Eric Cator

# The concave majorant of one-sided Brownian motion

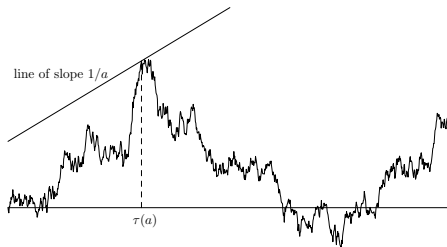


Figure:  $\tau(a) = \operatorname{argmax}_x \{ W(x) - \frac{x}{a} : x \geq 0 \}$

We have again the **switch relation**:

$$S_t \geq 1/a \iff t \leq \tau(a),$$

where  $S_t$  is the slope of the concave majorant at time  $t$ .



# The argmax process $a \mapsto \tau(a)$ for Brownian motion

## Theorem (Groeneboom (1983))

- ① *The argmax process  $a \mapsto \tau(a)$  is a time inhomogeneous process with independent increments, and, for  $u > 0$ ,*

$$\frac{\mathbb{P}\{\tau(a+h) - \tau(a) \in du \mid \tau(a) = t\}}{h} \sim \frac{e^{-u/(2a^2)}}{a^2 \sqrt{2\pi u}} du, \quad h \downarrow 0.$$

- ② *Let  $N(a, b)$  be the number of jumps of  $\tau$  in  $[a, b]$ . Then*

$$N(a, b) \stackrel{\mathcal{D}}{=} \text{Poisson}(\log(b/a)).$$

- ③ *As a consequence of 2:*

$$\{N(a, b) - \log(b/a)\} / \sqrt{\log(b/a)} \xrightarrow{\mathcal{D}} N(0, 1), \quad b/a \rightarrow \infty.$$

## Corollary (Groeneboom (1983))

- 1 *Brownian motion on  $[0, \infty)$  can be decomposed into the argmax process  $\tau$  and Brownian excursions.*
- 2 *If  $S_n$  is the slope of the concave majorant of the uniform empirical process  $U_n = \sqrt{n}\{\mathbb{F}_n - F\}$  on  $[0, 1]$ , then*

$$\left\{ \int_0^1 S_n(t)^2 dt - \log n \right\} / \sqrt{3 \log n} \xrightarrow{\mathcal{D}} N(0, 1).$$

Part 2 uses Doob's transformation (to go from Brownian motion to Brownian bridge) and Hungarian embedding.

Similar methods yield for the **number of jumps**  $N_n$  of the concave majorant of the uniform empirical process  $U_n = \sqrt{n}\{\mathbb{F}_n - F\}$ :

Theorem (Sparre Andersen (1954))

$$\{N_n - \log n\} / \sqrt{\log n} \xrightarrow{\mathcal{D}} N(0, 1).$$

# Ronald Pyke



## Theorem (Groeneboom and Pyke (1983))

If  $S_n$  is the slope of the concave majorant of the uniform empirical process  $U_n = \sqrt{n}\{\mathbb{F}_n - F\}$  on  $[0, 1]$ , then

$$\left\{ \int_0^1 S_n(t)^2 dt - \log n \right\} / \sqrt{3 \log n} \xrightarrow{\mathcal{D}} N(0, 1).$$

Order the induced spacings between locations of vertices of the least concave majorant:

$$D_{n0}; D_{n1,1}, \dots, D_{n1,J_{n1}}; \dots; D_{ni,1}, \dots, D_{ni,J_{ni}}; \dots$$

where there are  $J_{ni}$   $i$ -step spacings. Then:

$$\int_0^1 S_n(t)^2 dt = \sum_{i=1}^n \left\{ \sum_{j=1}^{J_{ni}} \frac{i^2}{nD_{n,ij}} - 1 \right\}.$$

Replace this by:

$$\sum_{i=1}^n \left\{ \sum_{j=1}^{N_i} \frac{i^2}{S_{n,ij}} - 1 \right\}.$$

where (independently)  $N_i \sim \text{Poisson}(1/i)$ ,  $S_{n,ij} \sim \Gamma(1, i)$  and condition on

$$\sum_{i=1}^n iN_i = n, \quad \sum_{i=1}^n \sum_{j=1}^{N_i} S_{n,ij} \sim n.$$

## Further work on this topic

Pitman (1983): interpretation in terms of Bessel processes and path decomposition (David Williams).

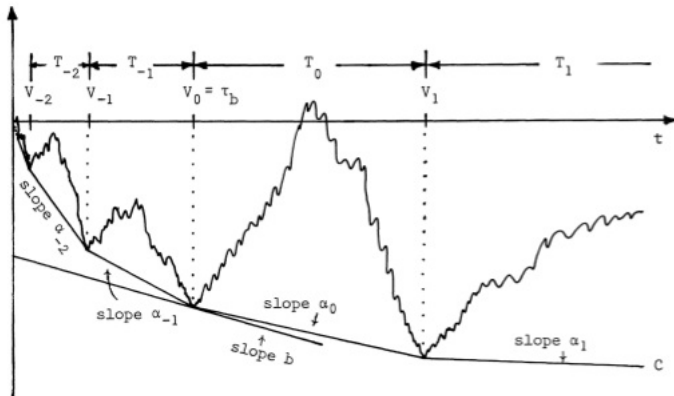


Figure 1. Convex minorant of  $B$  is  $C$ . The vertex set consists of the points  $\dots, V_{-2}, V_{-1}, V_0, V_1, V_2, \dots$

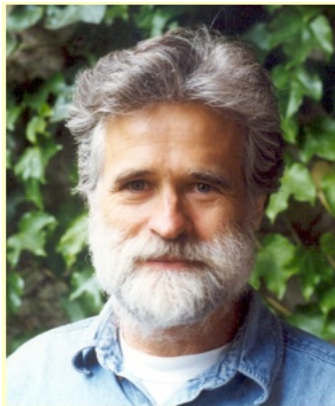
## Theorem (Pitman (1983))

Fix  $b \in (-\infty, 0)$  and let  $T_0 = \tau_b = \operatorname{argmin}\{W(x) - bx\}$ . Then:

- (i) *The next slope  $\alpha_0$  of the convex minorant is uniformly distributed on  $(b, 0)$ , and conditionally on  $\alpha_0, \dots, \alpha_n$ , the next slope  $\alpha_{n+1}$  is uniform on  $(\alpha_n, 0)$ .*
- (ii) *The preceding slope  $\alpha_{-1}$  has density  $|b|x^{-2}$  on the interval  $(-\infty, b)$ , and, conditional on  $\alpha_{-n}, \dots, \alpha_{-1}$ ,  $\alpha_{-n-1}$  has density  $|\alpha_{-n}|x^{-2}$  on  $(-\infty, \alpha_{-n})$ .*
- (iii) *The sequences  $\{\alpha_i, i < 0\}$  and  $\{\alpha_i, i \geq 0\}$  are independent.*
- (iv) *Conditional on all the slopes  $\alpha_i$ , the lengths of the segments  $T_i$  are independent, and  $T_i$  has a gamma( $\frac{1}{2}, \frac{1}{2}\alpha_i^2$ ) distribution:*

$$\mathbb{P} \{ T_i \in dt \mid \alpha_i = a, \alpha_j, j \neq i \} = \frac{|a|}{\sqrt{2\pi t}} e^{-\frac{1}{2}a^2 t} dt.$$

Jim Pitman



[Çınlar \(1992\)](#): connection with queueing systems (“Sunset over Brownistan”),

[Balabdaoui and Pitman \(2011\)](#): maximal difference between Brownian bridge and its concave majorant,

[Pitman and Ross \(2012\)](#): greatest convex minorant of Brownian motion, meander, and bridge,

[Pitman and Uribe Bravo \(2012\)](#): the convex minorant of a Lévy process.



The process  $a \mapsto V(a) = \operatorname{argmax}\{W(t) - (t - a)^2\}$

Figure 4.1 in Groeneboom (1989) (PTRF):

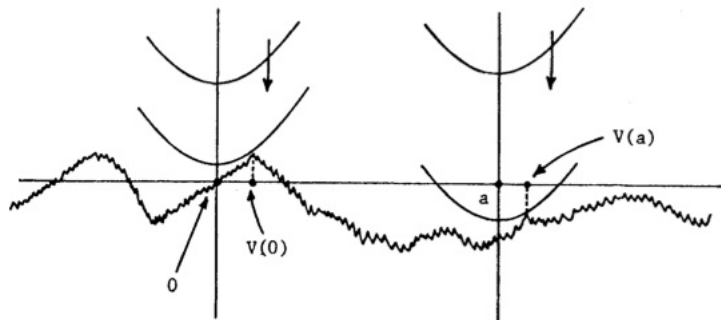


Fig. 4.1

(Stationary) point process of locations of maxima:

$$V(a) = \operatorname{argmax}_x \{W(x) - (x - a)^2 \text{ is maximal}\}.$$

Theorem (Groeneboom (1985), Groeneboom, Hooghiemstra, and Lopuhaä (1999))

Let  $f$  be a twice differentiable decreasing density on  $[0,1]$ . Then (under some additional conditions) we have, with

$$\mu = E|V(0)| \int_0^1 |4f'(t)f(t)|^{1/3} dt,$$

$$n^{1/6} \left\{ n^{1/3} \int_0^1 |\hat{f}_n(t) - f(t)| dt - \mu \right\} \xrightarrow{\mathcal{D}} N(0, \sigma^2),$$

where  $\sigma^2 = 8 \int_0^\infty \operatorname{covar}(|V(0)|, |V(c) - c|) dc$ .

## Durot-Lopuhaä $k$ -sample tests

**Setting:** we want to test the hypothesis

$$H_0 : f_1 = f_2 = \cdots = f_J \quad \text{against} \quad H_1 : f_i \neq f_j, \text{ for some } i \neq j,$$

where  $f_j : [0, B] \rightarrow \mathbb{R}$  is decreasing. The  $f_j$  can be densities, regression functions, etc. Consider the test statistic:

$$T_N = \sum_{j=1}^J \int_0^B \left| \hat{f}_{j,n_j}(t) - \hat{f}_N(t) \right| dt, \quad N = \sum_{j=1}^J n_j,$$

where  $\hat{f}_{j,n_j}$  is the isotonic estimate in the  $j$ th sample of size  $n_j$  (for example the Grenander estimate), and  $\hat{f}_N$  is the isotonic estimate in the combined samples.

We want to use the bootstrap to find a critical value  $c$  such that (for example):

$$\mathbb{P} \{ T_N \geq c \} = 0.05.$$

# Rik Lopuhaä and Cécile Durot



Durot and Lopuhaä: under a number of regularity conditions there are constants  $\mu$  and  $\sigma$  such that

$$N^{1/6} \left\{ N^{1/3} T_N - \mu \right\} / \sigma \xrightarrow{\mathcal{D}} N(0, 1), \quad (4)$$

under  $H_0$ .

$\mu$  depends on  $f$  and  $f'$ , if  $f$  is the common density or regression function. So we cannot use (4) to find the critical value without first estimating  $f'$ .

Consider:  $f_\lambda(x) = \lambda e^{-\lambda x} / (1 - e^{-3\lambda})$  on  $[0, 3]$ .

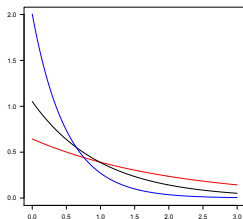


Figure: Truncated exponential densities with  $\lambda$  equal to 0.5 (red), 1

## Bootstrapping the critical value

Will bootstrapping from the Grenander estimator work to find the critical value? We try it out!

**General procedure:** We generate 10,000 sets of 3 samples of size 100, where the first two samples are from a truncated standard exponential density ( $\lambda = 1$ ) on  $[0, 3]$  and the third sample from a truncated exponential density with varying parameter  $\lambda$ .

**Bootstrap procedure:** For each of the original samples we generate 10,000 bootstrap samples from the Grenander estimate  $\hat{f}_N$  for the combined original samples. Next we count how many times the test statistics in the original sample exceed the 95% percentile of the test statistics in the 10,000 bootstrap samples. This gives an estimate of the power of the tests.

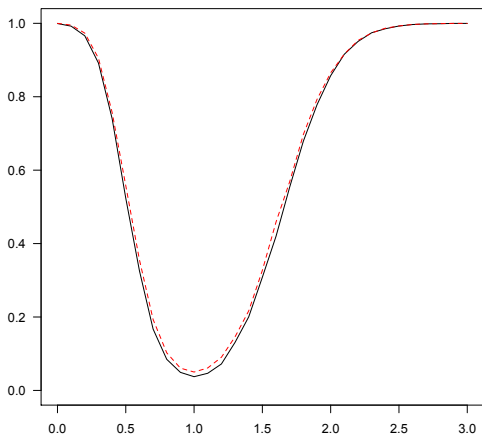
## Verification procedure

- 1 We first generate 10,000 samples of size 300 from the mixture density:

$$g_{\lambda}(x) = \frac{2}{3} \frac{e^{-x}}{1 - e^{-3}} + \frac{1}{3} \frac{e^{-\lambda x}}{1 - e^{-3\lambda}}, \quad x \in [0, 3],$$

and compute the test statistics for each sample. Then we determine the 95% percentiles for the values so obtained for the two statistics. This gives the critical values for [step 2](#):

- 2 We generate 10,000 sets of 3 samples of size 100, where the first two are generated from a standard truncated exponential and the third from an truncated exponential density with parameter  $\lambda$  and count how many times the test statistics exceed the critical values obtained in the first step. This gives estimates of the power functions.



**Figure:** Estimate of the power of the Durot-Lopuhaä test on the interval  $[0, 3]$ . Solid: bootstrap estimate from the Grenander estimate; red and dashed: direct estimate of the real power.



## Concluding remarks

- Local limit distribution of MLE for interval censoring, case 2, non-separated case, is still only conjectured.
- Local limit of MLE for deconvolution is still only conjectured.
- Local limit of MLE for bivariate current status is still unknown. There are estimators, achieving the  $n^{1/3}$ -rate.
- Limit of LS estimator for convex regression has been determined, but the structure of the limiting process has not been analytically determined.
- Convex envelope of Brownian motion without drift is very different from convex envelope of Brownian motion with parabolic drift.
- Possibly the bootstrapping of global statistics can be done from the Grenander estimator, as suggested by simulations.

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